

# TEERATHAM (TJ) VITCHUTRIPOP

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51 Prospect St, New Haven, CT 06511

## EDUCATION

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**Yale University** New Haven, CT  
Ph.D. in Computer Science 2024 – Present  
*Advisor:* Daniel Rakita

**University of Virginia** Charlottesville, VA  
B.S. Computer Science and B.A. Philosophy 2020 – 2024  
*GPA:* 3.885 | *Honors:* Highest Distinction, Raven Society

## RESEARCH EXPERIENCE

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**Yale University, Department of Computer Science** New Haven, CT  
*Graduate Research Assistant – Applied Planning, Learning, and Optimization (APOLLO) Lab* Aug. 2024 – Present  
Advised by **Daniel Raktia**

- Proposing and developing imitation and reinforcement learning algorithms for multi-agent mobile manipulation systems.
- Brainstorming computer vision approaches for 3D view reconstruction to assist surgeons in robotic surgery.

**Carnegie Mellon University, Robotics Institute** Pittsburgh, PA  
*RI Summer Scholar (RISS) – Robots Perceiving and Doing (R-PAD) Lab* Jun. 2023 – June 2024  
Advised by **David Held**

- Proposed and developed novel unsupervised architecture, *TaskSeg*, for segmenting task-relevant objects in robot manipulation tasks through video demonstrations.
- Applied optical flow on video demonstration frames to generate pseudo-label masks used to train a segmentation model for a downstream robot manipulation policy.
- Performed comparative experiments with a model trained on ground truth data, showing comparable results (~5% mIoU difference on most tasks), and ablation studies on different flow aggregation methods.

**University of Virginia, Link Lab** Charlottesville, VA  
*Undergraduate Research Assistant – Collaborative Robotics Lab* Aug. 2021 – May 2024  
Advised by **Tariq Iqbal**

- Proposed and developed novel deep reinforcement learning algorithm, *LASSO*, to tackle dynamic goal manipulation tasks using an autoencoder and contrastive learning-based architecture, addressing the representation learning bottleneck of RL algorithms and improving upon state-of-the-art performance.
- Conducted experiments in custom OpenAI Gym MuJoCo environments to benchmark task performance.
- Developed behavior trees in ROS using PyTrees for robotic control in human-robot demonstrations.

## PUBLICATIONS

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### 2024

- B. Eisner, E. Cai, O. Donca, **T. Vitchutripop**, and D. Held, *Sequential Object-Centric Relative Placement Prediction for Long-Horizon Imitation Learning*, Learning Effective Abstractions for Planning (LEAP) Workshop @ Conference on Robot Learning 2024 [[paper](#)]
- J. Brown\*, **T. Vitchutripop\***, E. Cai, J. Wang, and D. Held, *Unsupervised Deep Instruction Tuning for Few Shot Object Segmentation* (Submitted) [[website](#)]
- M. S. Yasar, **T. Vitchutripop**, and T. Iqbal, *LASSO: Learning Latent Policies via State Space Modeling* (Submitted)
- R. Klein-Seetharaman, R. Xue, B. Li, R. Tsai, B. Goldstein, C. Liang, **T. Vitchutripop**, Q. Wang, L. Merz Hoffmeister, X. Sun, D. Rakita, *APOLLO Toolbox: A Flexible, Multi-language Planning, Learning, and Optimization Software Suite* (Submitted)

## 2023

T. Vitchutripop, J. Wang, and D. Held, *TaskSeg: Task-Specific Object Segmentation Through Demonstration*, RISS Working Papers Journal 2023 [[paper](#)] [[video](#)] [[poster](#)]

## PRESENTATIONS

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- TaskSeg: Task-Specific Object Segmentation Through Demonstration [[poster](#)] August 2023  
*Poster Presentation, Robotics Institute Summer Scholar Showcase, Carnegie Mellon University*
- LASSO: Learning Latent Policies via State Space Modeling [[slides](#)] April 2023  
*Oral Presentation, Undergraduate Engineering Research and Design Symposium, University of Virginia (Awarded Best Oral Presentation)*
- LASSO: Learning Latent Policies via State Space Modeling [[slides](#)] March 2023  
*ACC Meeting of the Minds Conference, Virginia Tech (1 of only 5 selected to represent UVA)*

## HONORS & GRANTS

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- Louis T. Rader Outstanding Undergraduate Research Award** 2024, 2023  
Department of Computer Science, University of Virginia
- CRA 2024 Outstanding Undergraduate Researcher Award (Honorable Mention)** 2024  
Computing Research Association
- Robotics Institute Summer Scholar (RISS) [NSF REU Program] (7.8% acceptance rate)** 2023  
Robotics Institute, Carnegie Mellon University
- Best Oral Presentation (1<sup>st</sup> place)** 2023  
2023 Undergraduate Engineering Research and Design Symposium, University of Virginia
- Double Hoo Research Grant Award** 2022  
Office of Citizen Scholar Development, University of Virginia

## SKILLS & LANGUAGES

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**Programming Languages:** Python, Java, C++, C, JavaScript, TypeScript, Assembly  
**Machine Learning and Robotics Frameworks:** PyTorch, TensorFlow & Keras, OpenAI Gym, MuJoCo, ROS, OpenCV, Scikit-Learn, NumPy, Pandas, PyTrees, PyTorch Lightning, RLBench  
**Other Tools and Frameworks:** GitHub, Bitbucket, Docker, Weights and Biases, Singularity, Slurm, Visual Studio Code, JupyterLab, Linux, React, Node.js, Airtable, Excel, MATLAB, Autodesk Fusion 360

## PROFESSIONAL EXPERIENCE

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- National Science Foundation** Alexandria, VA  
*Policy and Data Science Intern – UVA-MIT Policy Internship Program* June 2022 – Feb 2023
- Contributed towards efforts to publish and open-source innovation and entrepreneurship application data for the NSF Engines program, developing data cleaning pipelines, data visualization prototypes, and a public-facing database for collaboration in Airtable used by 5000+ users and featured in multiple publications (e.g., [Forbes](#), [Heartland Forward](#), [SSTI](#)).
  - Leveraged state-of-the-art large language models and natural language processing techniques to extract entities from records and reports, unveiling companies/startups spun off from NSF-funded research.
- Interop.io (formerly Cosaic)** Charlottesville, VA  
*Software Engineering Intern* June 2021 – Aug. 2021
- Designed headless UI unit tests for React components (increasing coverage from 0% to 50%) and end-to-end regression tests for 2 different parts of the product.
  - Refactored existing legacy React components, converting them to TypeScript for build-time type safety and importing them into Storybook to support modular testing.

## TEACHING EXPERIENCE

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**CS 2120 Discrete Mathematics and Theory 1**, University of Virginia

Charlottesville, VA

*Teaching Assistant*

Feb. 2021 – May 2024

- Planned and co-lectured classes on quantifier logic and entailment to 100+ students.
- Guide and support students on course content during in-class activities, office hours, and after lectures.
- Strategize with professors and other teaching assistants about optimal ways to deliver class content.

**STS 3020 Science and Technology Policy for Interns**, University of Virginia

Charlottesville, VA

*Teaching Assistant*

Aug. 2022 – May 2023

- Supported instructor in program recruitment and course design + operations.
- Coordinated and moderated alumni guest speaker panels.
- Developed and maintained UVA Policy Internship Program [website](#).

## LEADERSHIP & SERVICE

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**HooHacks**, University of Virginia

Charlottesville, VA

*Marketing Committee Co-Chair*

Sept. 2020 – May 2024

- Lead committee members and collaborate with HooHacks executive board on planning marketing campaign and strategy for HooHacks, UVA's premier student-run hackathon with 1000+ participants.
- Established stronger relationships with organizations for underrepresented groups in STEM and minority serving institutions to make events more inclusive.

**Charlottesville Debate League (CDL)**, University of Virginia

Charlottesville, VA

*Teacher (2020-2023) | Head Teacher (2022)*

Sept. 2020 – May 2023

- Mentored 30+ middle school students on extemporaneous speaking and public forum debate.
- Discuss with teachers on best ways to implement curriculum and maintain high student engagement.
- Analyze effective teaching strategies with other CDL teachers at 10+ schools.